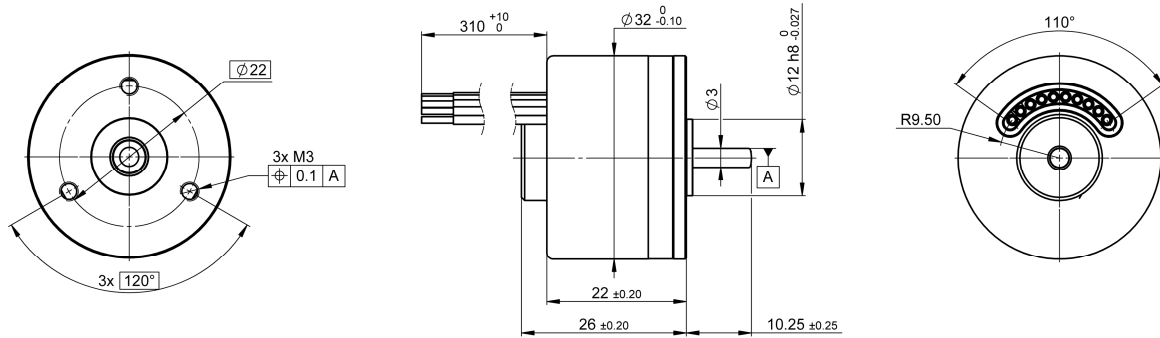


**BRUSHLESS MOTOR – HALL SENSORS OR SENSORLESS**

**Motor parameters (25°C)**

		1	2
Phase-Phase resistance	ohm	0.19	0.75
Torque constant	mNm/A	1.72	3.44
Back EMF constant	V/Krpm	0.18	0.36
Phase-Phase inductance	mH	0.06	0.24
Motor constant	mNm/vW	4.0	4.0
Rotor inertia	10 <sup>-7</sup> Kg.m <sup>2</sup>	1.3	1.3
Mechanical time constant	ms	8.3	8.3
Electrical time constant	ms	0.32	0.32

**Dynamic parameters at nominal voltage (25°C)**

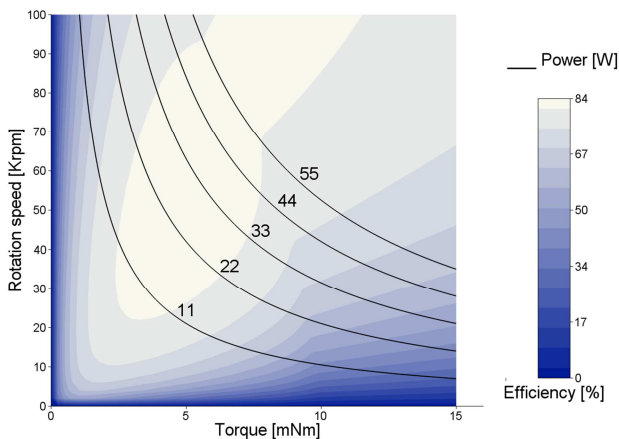
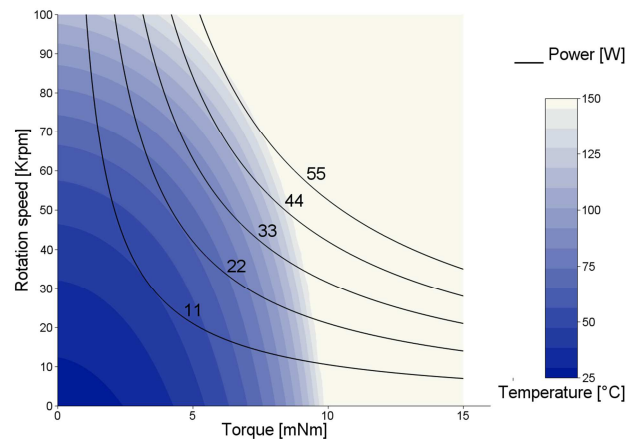
		1	2	
<b>No load</b>	Nominal voltage	V	12	24
	Current	mA	340	170
	Speed	rpm	66'900	66'900
<b>Peak efficiency</b>	Electrical input power	W	4.1	4.1
	Current	A	4.6	1.9
	Torque	mNm	7.4	6.1
	Speed	rpm	61'800	62'800
	Electrical input power	W	56	45
Mechanical output power	W	48	40	
Efficiency	%	86%	89%	

**Motor specifications**

Number of pole pairs	-	1
Number of phases	-	3
Motor Mass	g	60
Thermal resistance	°C/W	20
Max permissible winding temperature	°C	155

**Motor configurations**

All Electromag motors are available with custom configurations. Mechanical interface, windings and motor characteristics can be customized for each application. This generic outline drawing only shows the envelope of the motor. For detail dimensions and tolerances, please contact the factory.

**Efficiency & Mechanical power**

**Temperature & Mechanical power**

**Notes**

Efficiency and temperature maps are obtained using a heat sink that reduces the motor thermal resistance by 50% (typical case). Continuous operation is allowed until the maximum winding temperature has been reached. Beyond this point, intermittent operation or additional cooling should be considered.

Rev 2014.08. Specifications are subject to change without prior notice